Deterministic Minimum Steiner Cut in Maximum Flow Time

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- (Global) Minimum cut: $m^{1+o(1)}$, "almost-linear" (Li, STOC 2021)
- (s t) Maximum flow: $m^{1+o(1)}$, "almost-linear" (vdBCKLPGSS, FOCS 2023)

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Ultimate goal: near-linear time algorithms!

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Given undirected, weighted graph G(V, E) and a subset of vertices $T \subseteq V$ (called terminals), find the subset of edges of minimum total weight disconnecting *any* pair of vertices in T.



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Deterministic near-linear minimum Steiner cut?

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Previous Work: Minimum Steiner Cut

Folklore: $n-1 \ s-t$ min-cuts (calls to any blackbox max-flow algorithm).

Previous Result: Li, Panigrahi (FOCS 2020)

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Deterministic polylogarithmic maximum flows requires $m^{1+O(1)}$ overhead! Ideally we would like near-linear max-flow and **near-linear overhead**.

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Bottleneck!

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Bottleneck! Necessary?

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Theorem 1: Faster Deterministic Minimum Steiner Cut

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There exists a deterministic minimum Steiner cut algorithm with polylogarithmic maximum flow calls and <u>near-linear</u> overhead

- Deterministic near-linear maximum flow algorithm is the only barrier towards deterministic near-linear minimum Steiner cut.
- 2 Runtime improvement by forgoing expander decomposition

A cluster C is called s-strong if any cut of size $< \delta$ splits the cluster with at most s volume on one side.

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 - Weighted: HLRW (SODA 2024)

Our Results: Terminal-Based Partitioning

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Definition: ψ -terminal-sparsity

A cut S is called ψ -terminal-sparse if

$$\frac{w(S,\bar{S})}{\min(|S \cap T|,|\bar{S} \cap T|)} < \psi \tag{1}$$

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- **2** The total weight of edges between clusters is at most $\tilde{O}(\delta \cdot |T|)$
- So For any cluster, any cut of size < δ either does not split the cluster or splits edges within the cluster with total weight > δ/polylog(n)

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Algorithm partitioning weighted graph into clusters such that

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- **②** The total weight of edges between clusters is at most $\tilde{O}(\delta \cdot |T|)$
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Uses $\log^2 n$ maximum flows and near-linear overhead.

- (1) and (2) directly generalize s-strong partitions to terminals
- (3) ensures few clusters are split, (1) ensures clusters are split unbalanced!

• Khandekar, Rao, Vazirani (J. ACM 2009)

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- Key idea: Two players, iteratively embed low-congestion expander into graph G(V, E)
- Begin by instantiating an empty graph *H* with vertices *V*, called the "cut graph"



Cut-Matching Game Iteration

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Figure: Cut Player: Bipartition

Cut-Matching Game Iteration

Cut player finds bipartition of cut graph *H* containing sparse cut
 Matching player computes maximum flow between bipartition on original graph *G* and embeds the flow as a matching in *H*

• If flow cannot be successfully routed, we get a sparse cut



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- If flow cannot be successfully routed, we get a sparse cut
- **Solution** After $\log^2 n$ rounds, G is guaranteed to be an edge-expander.



Figure: Certify Expander!

• Goal: Find terminal-sparse cut or certify none exist

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- Key idea: Embed low-congestion s-strong graph on terminals
- Begin by instantiating an empty cut-graph of terminals *T*, instead of all vertices



Figure: Graph G (black), terminals (red)



Figure: Cut Graph H (orange)

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Terminal Cut-Matching Game Iteration

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Terminal Cut-Matching Game Iteration

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Figure: Cut Player: Bipartition

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Terminal Cut-Matching Game Iteration

- Cut player finds bipartition of cut graph H containing sparse cut.
- Matching player computes maximum flow between terminal partition on original graph G and embeds flow as matching edges in cut graph.
- **3** After $\log n$ rounds, we certify G as a terminal-strong cluster.





Figure: Certify Cut-Graph *s*-strong

Figure: Certify Graph s-terminal-strong!

• What happens when we can't make a complete flow?



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Figure: No Flow?

- Original cut-matching game: sparse cut
- Terminal cut-matching game: terminal-sparse cut, since terminals are sources/sinks

Two cases to consider:

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Balanced Cut: Recurse on both sides



Figure: Small flow, balanced cut

Two cases to consider:

- Balanced Cut: Recurse on both sides
- Onbalanced Cut: Larger side is terminal-strong, recurse on smaller side



Figure: Small flow, balanced cut



Figure: Small flow, unbalanced cut

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Image: A mathematical states of the state

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Future Directions:

- Near-linear maximum flow algorithm (randomized or deterministic)
- ② Terminal-based partitioning algorithm as subroutine?

Questions?

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